SIEMENS

Data sheet

6ES7515-2TN03-0AB0



SIMATIC S7-1500T, CPU 1515T-2 PN, central processing unit with 1.5 MB work memory for program and 4.5 MB for data, 1st interface: PROFINET IRT with 2-port switch, 2nd interface: PROFINET RT, 6 ns bit performance, SIMATIC Memory Card required * *** approvals and certificates according to entry 109816881 at support.industry.siemens.com to be observed! ****

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Product type designation CPU 1515T-2 PN HW functional status FS01 Firmware version V3.0 Product function V3.0 Product function V3.0 Product function V3.0 Product function V3.0 Isochronous mode Yes; I&M0 to I&M3 Isochronous mode Yes; Distributed and central; with minimum OB 6x cycle of 375 µs (distributed) and 1 ms (central) Configuration control (distributed) and 1 ms (central) Via dataset Yes Display Screen diagonal [cm] Screen diagonal [cm] 6.1 cm Control elements 8 Number of keys 8 Mode buttons 2 Supply voltage 2 Rated value (DC) 24 V permissible range, lower limit (DC) 19.2 V permissible range, upper limit (DC) 28.8 V Reverse polarity protection Yes Mains buffering 5 ms • Mains/voltage failure stored energy time 5 ms	Product type designation	CDI 1515T 2 DN
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Reverse polarity protection Yes Mains buffering • Mains/voltage failure stored energy time 5 ms	permissible range, lower limit (DC)	19.2 V
Mains buffering • Mains/voltage failure stored energy time 5 ms	permissible range, upper limit (DC)	28.8 V
Mains/voltage failure stored energy time 5 ms	Reverse polarity protection	Yes
	Mains buffering	
Repeat rate min	 Mains/voltage failure stored energy time 	5 ms
	Repeat rate, min.	1/s
Input current	Input current	
Current consumption (rated value) 0.83 A	Current consumption (rated value)	0.83 A
Current consumption, max. 1.03 A	Current consumption, max.	1.03 A
Inrush current, max. 1.15 A; Rated value	Inrush current, max.	1.15 A; Rated value
1 ² t 0.6 A ² ·s	l²t	0.6 A ² ·s
Power	Power	
Infeed power to the backplane bus 12 W	Infeed power to the backplane bus	12 W
Power consumption from the backplane bus (balanced) 6.2 W	Power consumption from the backplane bus (balanced)	6.2 W
Power loss	Power loss	
Power loss, typ. 7.9 W	Power loss, typ.	7.9 W
Memory	Memory	
Number of slots for SIMATIC memory card 1	Number of slots for SIMATIC memory card	1
SIMATIC memory card required Yes	SIMATIC memory card required	Yes
Work memory	Work memory	
• integrated (for program) 1.5 Mbyte	 integrated (for program) 	
• integrated (for data) 4.5 Mbyte	integrated (for data)	4.5 Mbyte

Load memory	
Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	62 65/18
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	6 ns
for word operations, typ.	7 ns
for fixed point arithmetic, typ.	9 ns
for floating point arithmetic, typ.	37 ns
CPU-blocks	57 115
Number of elements (total) DB	8 000; Blocks (OB, FB, FC, DB) and UDTs
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	4.5 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	0 65 525
Number range	0 65 535
• Size, max. FC	1 Mbyte
	0 65 535
Number rangeSize, max.	1 Mbyte
• Size, max. OB	
• Size, max.	1 Mbyte
 Size, max. Number of free cycle OBs 	100
Number of time alarm OBs	20
	20
 Number of delay alarm OBs Number of cyclic interrupt OBs 	
	20; With minimum OB 3x cycle of 250 µs
Number of process alarm OBs	50
Number of DPV1 alarm OBs	3
Number of isochronous mode OBs	2
Number of technology synchronous alarm OBs	2
 Number of startup OBs 	100
 Number of asynchronous error OBs 	4
 Number of synchronous error OBs 	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	512 kbyte; In total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 472 KB
Extended retentive data area (incl. timers, counters, flags), max.	4.5 Mbyte; When using PS 6 0W 24/48/60 V DC HF
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	

Retentivity adjustable	Yes
Retentivity preset	No
Local data	
 per priority class, max. 	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	8 192; max. number of modules / submodules
I/O address area	
Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
 Number of subprocess images, max. 	32
Hardware configuration	
Number of distributed IO systems	64; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
• integrated	2 9: A movimum of a CMa/CBa (DDOEIDUC, DDOEIDUE, Ethernat) and
● Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Rack	
Modules per rack, max.	32; CPU + 31 modules
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Туре	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
 supported 	Yes
 in AS, master 	Yes
• in AS, slave	Yes
on Ethernet via NTP	Yes
Interfaces	
Number of PROFINET interfaces	2
1. Interface	
Interface types	
• RJ 45 (Ethernet)	Yes; X1
Number of ports	2
 integrated switch 	Yes
Protocols	
IP protocol	Yes; IPv4
 PROFINET IO Controller 	Yes
PROFINET IO Device	Yes
 SIMATIC communication 	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy PROFINET IO Controller	Yes
Services	

	tion e
— Direct data exchangeYes; Requirement: IRT and isochronous mode (MRPD optional)— IRTYes— PROFlenergyYes; per user program— Prioritized startupYes; Max. 32 PROFINET devices— Number of connectable IO Devices, max.256; in total, up to 1 000 distributed I/O devices can be connected of AS-i, PROFIBUS or PROFINET— Of which IO devices with IRT, max.64— Number of connectable IO Devices for RT, max.256— of which in line, max.256— Number of IO Devices that can be simultaneously activated/deactivated, max.8— Updating timesThe minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user dataUpdate time for IRT250 µs to 4 ms; Note: In the case of IRT with isochronous Mode, the minimum update time of 375 µs of the isochronous OB is decisive for send cycle of 500 µs— for send cycle of 1 ms1 ms to 16 ms— for send cycle of 2 ms2 ms to 32 ms— for send cycle of 1 ms1 ms to 16 ms— for send cycle of 1 ms4 ms to 64 ms— With IRT and parameterization of "odd" send cycles2 ms to 32 ms— With IRT and parameterization of "odd" send cycles2 ms to 32 ms— for send cycle of 4 ms4 ms to 64 ms— With IRT and parameterization of "odd" send cycles2 ms to 32 ms— for send cycle of 4 ms4 ms to 64 ms— Update time = set "odd" send clock (any multiple of 125 µs: 375 µs)	tion e
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— for send cycle of 1 ms1 ms to 16 ms— for send cycle of 2 ms2 ms to 32 ms— for send cycle of 4 ms4 ms to 64 ms— With IRT and parameterization of "odd" send cyclesUpdate time = set "odd" send clock (any multiple of 125 µs: 375 µs)	325
 for send cycle of 2 ms for send cycle of 4 ms With IRT and parameterization of "odd" send cycles 2 ms to 32 ms 4 ms to 64 ms Update time = set "odd" send clock (any multiple of 125 μs: 375 μs, μs 3 875 μs) 	325
— for send cycle of 4 ms4 ms to 64 ms— With IRT and parameterization of "odd" send cyclesUpdate time = set "odd" send clock (any multiple of 125 μs: 375 μs, μs 3 875 μs)	325
- With IRT and parameterization of "odd" send cycles Update time = set "odd" send clock (any multiple of 125 μ s: 375 μ s, μ s 3 875 μ s)	325
cycles	625
Update time for RT	
— for send cycle of 250 μs 250 μs to 128 ms	
— for send cycle of 500 μs 500 μs to 256 ms	
— for send cycle of 1 ms 1 ms to 512 ms	
- for send cycle of 2 ms 2 ms to 512 ms	
- for send cycle of 4 ms 4 ms to 512 ms	
PROFINET IO Device	
Services	
— PG/OP communication Yes	
— Isochronous mode No	
— IRT Yes	
— PROFlenergy Yes; per user program	
— Shared device Yes	
— Number of IO Controllers with shared device, 4	
max.	
- activation/deactivation of I-devices Yes; per user program	
— Asset management record Yes; per user program	
2. Interface	
Interface types	
• RJ 45 (Ethernet) Yes; X2	
Number of ports	
integrated switch No	
Protocols	
IP protocol Yes; IPv4	
PROFINET IO Controller Yes	
PROFINET IO Controller Yes PROFINET IO Device Yes	
SIMATIC communication Yes	
Open IE communication Yes; Optionally also encrypted	
Web server Yes	
Media redundancy No	
PROFINET IO Controller	
Services	
- PG/OP communication Yes	
— Isochronous mode No	
— Direct data exchange No	
— IRT No	
— PROFlenergy Yes; per user program	
— Prioritized startup No	

 — Number of connectable IO Devices, max. 	
	32; In total, up to 1 000 distributed I/O devices can be connected via
	AS-i, PROFIBUS or PROFINET
 — Number of connectable IO Devices for RT, max. 	32
— of which in line, max.	32
— Number of IO Devices that can be	8; in total across all interfaces
simultaneously activated/deactivated, max.	
- Number of IO Devices per tool, max.	8
— Updating times	The minimum value of the update time also depends on communication
	share set for PROFINET IO, on the number of IO devices, and on the
Lindata tima far DT	quantity of configured user data
Update time for RT — for send cycle of 1 ms	1 ms to 512 ms
PROFINET IO Device	
Services	
— PG/OP communication	Yes
— Isochronous mode	No
— IRT	No
— PROFlenergy	Yes; per user program
— Prioritized startup	No
— Shared device	Yes
- Number of IO Controllers with shared device,	4
max.	
 activation/deactivation of I-devices 	Yes; per user program
— Asset management record	Yes; per user program
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
 Autonegotiation 	Yes
Autocrossing	Yes
 Industrial Ethernet status LED 	Yes
Protocols	
PROFIsafe	No
Number of connections	
 Number of connections, max. 	256; via integrated interfaces of the CPU and connected CPs / CMs
 Number of connections reserved for ES/HMI/web 	10
 Number of connections via integrated interfaces 	128
 Number of connections via integrated interfaces Number of S7 routing paths 	128 16
Number of S7 routing paths Redundancy mode	
Number of S7 routing paths Redundancy mode H-Sync forwarding	
Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy	16
Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy	16 Yes only via 1st interface (X1)
Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP
Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy — MRP	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported — MRPD	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT
Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported — MRPD — Switchover time on line break, typ.	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD
Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported — MRPD — Switchover time on line break, typ. — Number of stations in the ring, max.	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT
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Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported — MRPD — Switchover time on line break, typ. — Number of stations in the ring, max. SIMATIC communication PG/OP communication	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected
Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported — MRPD — Switchover time on line break, typ. — Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50
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 Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy Media redundancy MRP MRP MRP MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing Data record routing S7 communication, as server S7 communication, as client 	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes Yes Yes
 Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy Media redundancy MRP MRP MRP MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing Data record routing S7 communication, as server S7 communication, as client User data per job, max. 	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes Yes
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 Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy Media redundancy MRP MRP MRP MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing Data record routing S7 communication, as server S7 communication, as client User data per job, max. Open IE communication TCP/IP Data length, max. Supported ISO-on-TCP (RFC1006) Data length, max. UDP Data length, max. 	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes Yes Yes See online help (S7 communication, user data size) Yes 64 kbyte Yes Yes 2 kbyte; 1 472 bytes for UDP broadcast
 Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy Media redundancy MRP MRP interconnection, supported MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing Data record routing S7 communication, as server S7 communication, as client User data per job, max. Open IE communication TCP/IP Data length, max. several passive connections per port, supported ISO-on-TCP (RFC1006) Data length, max. UDP 	16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes Yes Yes See online help (S7 communication, user data size) Yes 64 kbyte Yes Yes

	Vee
	Yes
• DNS • SNMP	Yes Yes
• DCP	Yes
• LLDP	Yes
ELDP Encryption	Yes: Optional
Web server	ies, Optional
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
Runtime license required	Yes; "Medium" license required
OPC UA Client	Yes; Data Access (registered Read/Write), Method Call
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15,
	Basic256Sha256
 User authentication 	"anonymous" or by user name & password
 Number of connections, max. 	10
 Number of nodes of the client interfaces, recommended max. 	2 000
 — Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/C max. 	300
 — Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20
 — Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100
 Number of simultaneous calls of the client instructions for session management, per connection, max. 	1
 Number of simultaneous calls of the client instructions for data access, per connection, max. 	5
— Number of registerable nodes, max.	5 000
 — Number of registerable method calls of OPC_UA_MethodCall, max. 	100
 — Number of inputs/outputs when calling OPC_UA_MethodCall, max. 	20
OPC UA Server	Yes; Data Access (Read, Write, Subscribe), Method Call, Alarms & Condition (A&C), Custom Address Space
 Application authentication 	Yes
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss
— User authentication	"anonymous" or by user name & password
— GDS support (certificate management)	Yes
 — Number of sessions, max. — Number of accessible variables, max. 	48 100 000
 – Number of accessible valuables, max. – Number of registerable nodes, max. 	20 000
 Number of subscriptions per session, max. 	50
— Sampling interval, min.	100 ms
— Publishing interval, min.	100 ms
— Number of server methods, max.	50
 Number of inputs/outputs per server method, max. 	20
 — Number of monitored items, recommended max. 	4 000; for 1 s sampling interval and 1 s send interval
- Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
 — Number of nodes for user-defined server interfaces, max. 	30 000
 Alarms and Conditions 	Yes
— Number of program alarms	200
— Number of alarms for system diagnostics	100
Further protocols	
• MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	64
Program alarms	Yes
Number of configurable program messages, max.	10 000; Program messages are generated by the "Program_Alarm"

	block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	5 000
Number of simultaneously active program alarms	
 Number of program alarms 	1 000
 Number of alarms for system diagnostics 	200
 Number of alarms for motion technology objects 	160
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 8 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	Ver
 Status/control variable Variables 	Yes
Number of variables, max.	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
- of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	200, poi jou
Forcing	Yes
 Forcing, variables 	Peripheral inputs/outputs
 Number of variables, max. 	200
Diagnostic buffer	
• present	Yes
 Number of entries, max. 	3 200
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
STOP ACTIVE LED	Yes
Connection display LINK TX/RX	Yes
Supported technology objects	
Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
 Number of available Motion Control resources for 	2 400
technology objects	
Required Motion Control resources	
 per speed-controlled axis 	10
	40
— per positioning axis	80
— per positioning axis — per synchronous axis	80 160
 per positioning axis per synchronous axis per external encoder 	80 160 80
 per positioning axis per synchronous axis per external encoder per output cam 	80 160 80 20
 per positioning axis per synchronous axis per external encoder per output cam per cam track 	80 160 80
 per positioning axis per synchronous axis per external encoder per output cam 	80 160 80 20 160
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe 	80 160 80 20 160 40
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control 	80 160 80 20 160 40
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) 	80 160 80 20 160 40 120 2
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) 	80 160 80 20 160 40 120 2 2
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) for each set of kinematics 	80 160 80 20 160 40 120 2 2 20 30
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) for each set of kinematics Per leading axis proxy 	80 160 80 20 160 40 120 2 2 20
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) for each set of kinematics Per leading axis proxy kinematics functions 	80 160 80 20 160 40 120 2 20 30 30 3
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) for each set of kinematics Per leading axis proxy kinematics functions kinematics with up to 4 interpolating axes 	80 160 80 20 160 40 120 2 20 30 3 3 Yes; max. 3D + orientation
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) for each set of kinematics Per leading axis proxy kinematics functions kinematics with up to 4 interpolating axes kinematics with 5 or more interpolating axes 	80 160 80 20 160 40 120 2 2 20 30 3 3 Yes; max. 3D + orientation No
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) for each set of kinematics Per leading axis proxy kinematics functions kinematics with up to 4 interpolating axes user-defined kinematics 	80 160 80 20 160 40 120 2 2 20 30 3 3 Yes; max. 3D + orientation No No
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) for each set of kinematics Per leading axis proxy kinematics functions kinematics with up to 4 interpolating axes user-defined kinematics SIMATIC Safe Kinematics 	80 160 80 20 160 40 120 2 2 20 30 3 3 Yes; max. 3D + orientation No
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) for each set of kinematics Per leading axis proxy kinematics functions kinematics with up to 4 interpolating axes user-defined kinematics SIMATIC Safe Kinematics Number of positioning axes at motion control 	80 160 80 20 160 40 120 2 2 20 30 3 3 Yes; max. 3D + orientation No No
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) for each set of kinematics Per leading axis proxy kinematics functions kinematics with up to 4 interpolating axes user-defined kinematics SIMATIC Safe Kinematics Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) 	80 160 80 20 160 40 120 2 20 30 3 Yes; max. 3D + orientation No No No No No No
 per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per cam (10 000 points and 50 segments) for each set of kinematics Per leading axis proxy kinematics functions kinematics with up to 4 interpolating axes user-defined kinematics SIMATIC Safe Kinematics Number of positioning axes at motion control 	80 160 80 20 160 40 120 2 20 30 3 Yes; max. 3D + orientation No No No No

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stallation altitudes > 2 000 m, see manual
operating temperature of typically 40 °C, the
operating temperature of typically 50 °C, the
grated optimization for temperature
grated optimization for valves
er with integrated optimization
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